

Dave Wilson Director of Academic Programs National Instruments

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Dave Wilson

Steps in the Technology Design Process

Director of Academic, Training and Certification Programs National Instruments Corporation

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Engineering Grand ChallengesArarce half
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Parker or heating
Parker

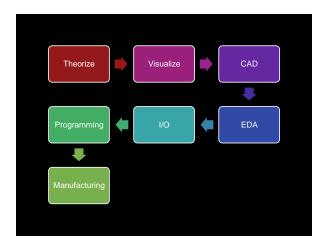
Manage the



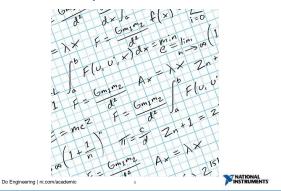
"The ensemble is the function..."



Dr. Alberto Sangiovani Vincentelli University of California at Berkeley



Learn the Theory



Theory is Important

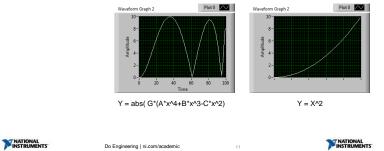
P Wave
$$\begin{split} P &= I^2 R = \frac{V^2}{R}, \\ v_p &= \sqrt{M/\rho}. \\ \text{S Wave} \\ \beta^2 &= \frac{\mu}{\rho}. \\ C(s) &= \left(K_P + K_I \frac{1}{s} + K_D s\right). \\ \text{PID} \\ \\ \text{De Engineering | nicom/academic} \\ y \end{split}$$

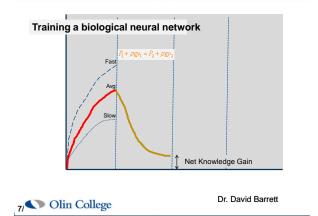
Using PID...

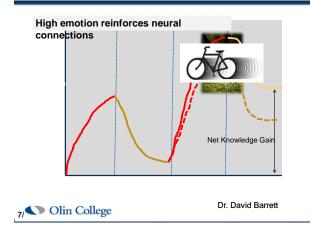
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Math... the shape maker



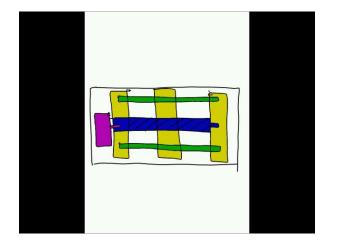


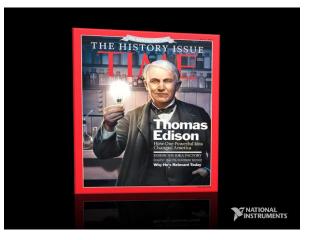




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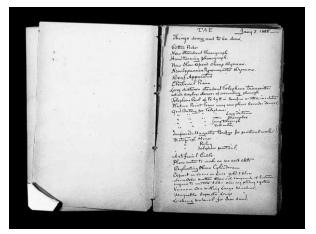
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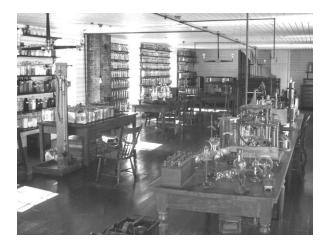




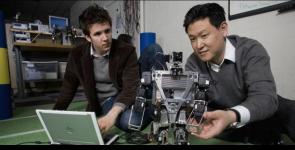
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Controls, Mechatronics, and Robotics Do Engineering: On One Platform from Concept to Proof

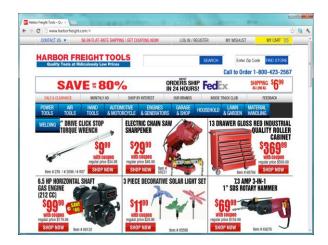


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Meghan Kerry Product Marketing Manager

Mechanical Prototyping

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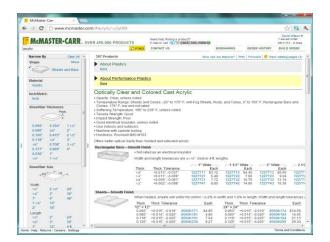












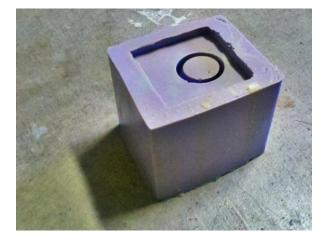












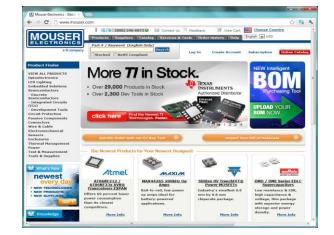








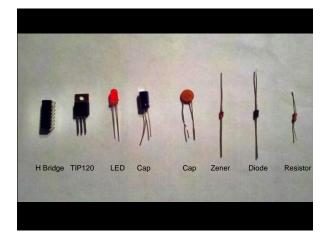


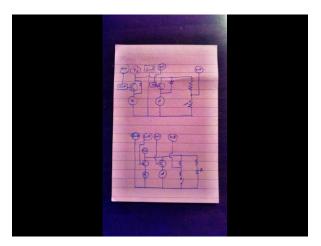


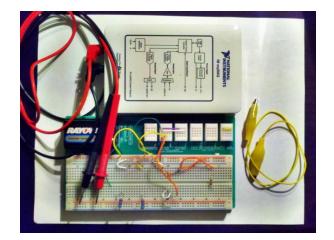
Electronic Prototyping

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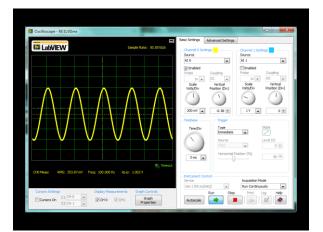






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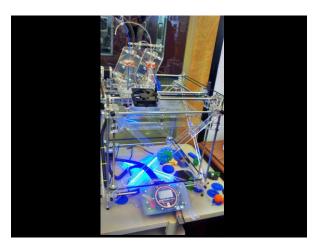


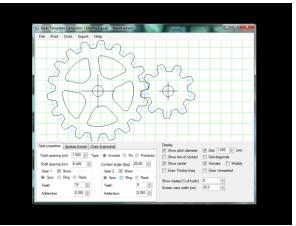
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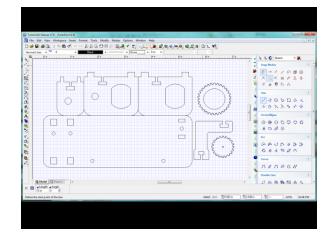


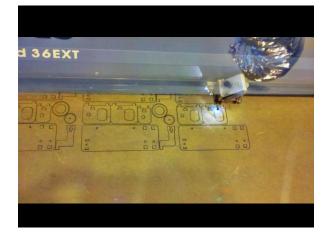
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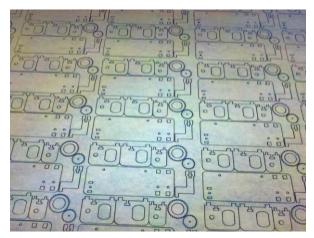




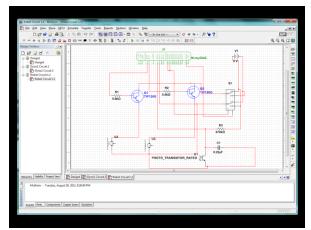


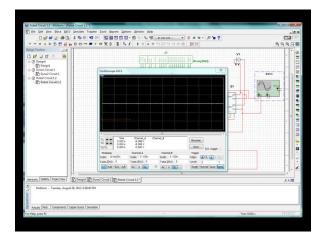


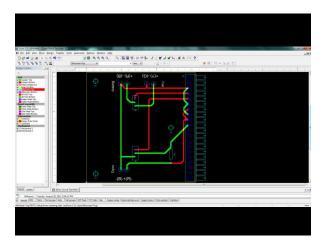




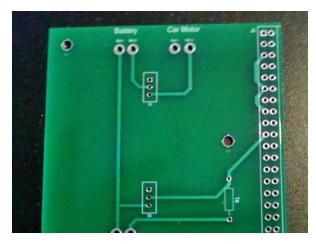










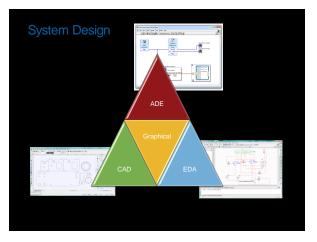




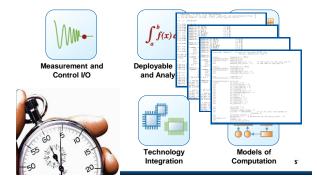
Programming

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Elements of Engineering Systems



Compatible Elements



Measurement and Control I/O

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Normalize Scale & Offset

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Deployable Math

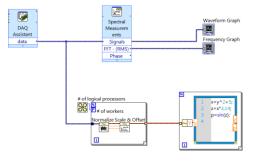
Technology Integration

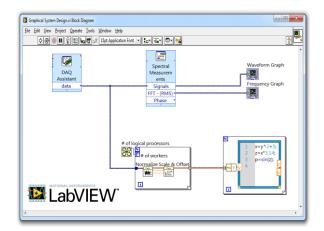


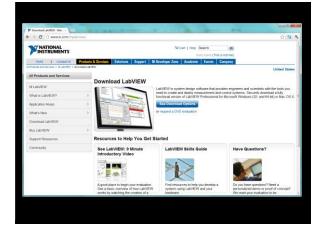
User Interface

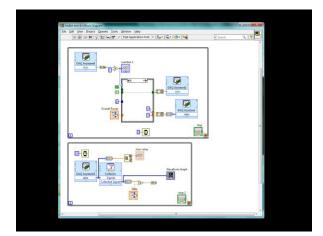


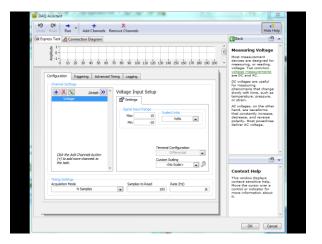
Easily Combined











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Home	2.5	Votlage [V Current [A] C	Calculated [W] Simulated [V	W] Actual [W]
Real World	1.5- 			
Theory	0.5-			
Problems Check	-0.5-1 90 Time			
Calibrate	25 25	30 40 50	5- Load	(
Acquire	Voltage [V] Current [A]	RPM 80	4- 1.45- 1.4- 3- 1.35-	Record Valu Clear Table
See Code	Voltage [V] Current [A]	×100	1.3- 2- 1.25-	Save Data
Help	Total Power Generated (mW-min)		1.2- 1.15- 0- 4 1.1-	User Name





Applications

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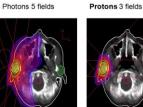
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CERN: MedAustron

Example: glandula parotid cancer

Photons 2 fields





Courtesy: University clinic for radiotherapy and radio-biology, AKH Vienna, Austria

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Application Notes

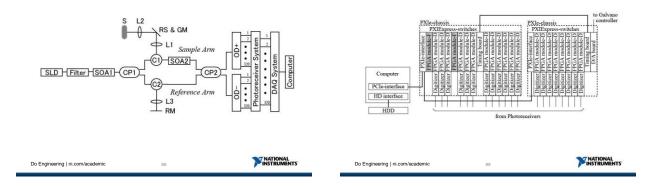
- Particle accelerator used for cancer therapy without damaging healthy tissue Wide energy range from 60 MeV to 800 MeV per nucleon with selectable beam energy in steps of 0.1 MeV
- 300,000 settings for the beam based on particle type, ion source, beam line, energy level, beam dimension, and spill length
- Concurrent beam control and reconfiguration in less than 250 msec Reconfigure the software on the FPGA for the next cycle while current beam is
- generated
- Distributed control system synchronously generates magnetic fields for 300 magnets by generating waveforms for power converters in real time at 2 kHz
- Second any generating waveforms for power converters in real time at 2 kHz
 Power converter synchronization at the microsecond level to generate/control the beam Power converters distributed over 800 m2 in access controlled area
- 500 beam cycles with different beam energies for a single medical irradiation session of about 2 minutes duration
- More than 20,000 shared variables for control, configuration, and monitoring · Solution completed in time because the researchers did not need to learn VHDL

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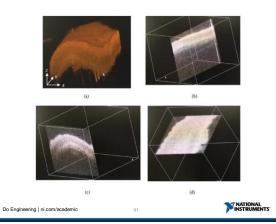
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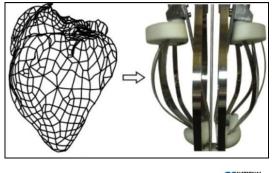
Optical Coherence Tomography







Heart Assist



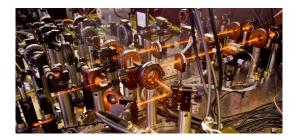
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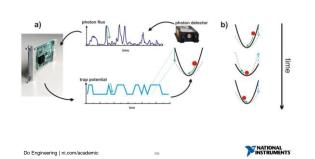


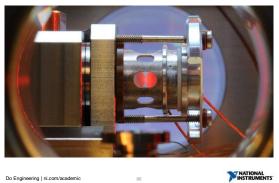
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Freezing an Atom



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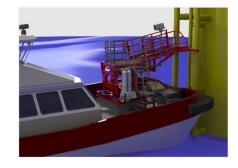




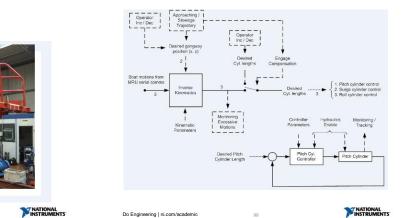
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Wave Motion Cancellation



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UC San Diego Multi-modal treaded rover

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$$\label{eq:construction} \begin{split} cb &= constructions (Constructions) (Constructions$$

litle	Controlling a Hydraulic Motion Compensated Gangway to Access Offshore Wind Turbines					
luthor	Andrew Clegg - Industrial Systems & Control LTD, UK					
Challenge						
	Creating a system to safely transfer personnel & equipment to offshore wind turbines in rolling seas & bad weather					
Solution	Using LabVIEW & cBIO to develop a movable gangway with an algorithm using boat motions to provide required hydraulic cylinder lengths to maintain position					
	wind turbines located further offshore, sea conditions become adverse					
	transferring personnel to sea based wind turbines for maintenance					
	moveable eaneway mounted on hydraulically actuated base on beat front					
	moveable gangway mounted on hydrauncally actuated base on boat front up & down oitch cylinder, forward & back surise cylinder, port/starboard roll cylinder					
	op & down pick cylinder, forward & back sorge cylinder, portystarboard roll cylinder					
	Used LVRT. FPGA & MathScript RT modules					
	did dynamic simulations to test control strat & hydraulic specs to meet perf tareets					
	sw emulator to test algorithm functionality					
	pwitched to real system to explore control loop performance for different loads, size, speed of motions, orientations //O & control algorithm on cRiO					
	Motion Reference Unit measures vessel motion, transmits positions & angles via serial link to MPU use mathscript nodes in LV for complex algorithms					
	Inverse kinematics transforms motion plan into joint actuator trajectories					
	calculate cylinder lengths & maintain gangway tip fixed in space					
	real time cascade control with feedforward & nonlinear compensation					
	cylinder length error for simulation & real testing showed simulation was reasonable rep of final system					
	development, implementation & factory testing took a little more than a year					
	sea trials confirm that range of motion compensation meets expectations from final factory testing					
	10 TATIONAL					

You have unprecedented access to the...

- · Theory
- Tools
- Materials
- Systems
- Instrumentation

• То...

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